

Distributional Modelling in R

Transformation Models

Thomas Kneib, Nikolaus Umlauf https://nikum.org/dmr.html

Motivation

• In an ideal world, all regression models would be of the form

$$Y = \mathbf{x}' \boldsymbol{\beta} + \varepsilon, \quad \varepsilon \sim \mathsf{N}(\mathbf{0}, \sigma^2),$$

which implies

$$\mathbf{Y} \sim \mathsf{N}(\mathbf{x}' \boldsymbol{eta}, \sigma^2)$$

or equivalently

$$rac{\mathbf{Y}-oldsymbol{x}oldsymbol{eta}}{\sigma}\sim\mathsf{N}(0,1)$$

Transformations

- Transformations are a common approach to make the normality assumption hold at least approximately, e.g.
 - the log-transformation

$$\log(Y) \sim N(\pmb{x}' \pmb{eta}, \sigma^2)$$

• or the Box-Cox-transformation

$$\left(\frac{\mathbf{Y}^{\lambda}-\mathbf{1}}{\lambda}\right)\sim \mathsf{N}(\mathbf{x}'\boldsymbol{\beta},\sigma^2).$$

Conditional Transformation Models

Conditional transformation models take this one step further and assume

$$h(Y|\boldsymbol{x}) \stackrel{\mathcal{D}}{=} Z \sim \mathsf{N}(0,1)$$

where $h(\cdot | \mathbf{x})$ is a covariate-dependent transformation function that is strictly increasing in y.

• Can be reversed to the generative model

$$Y \stackrel{\mathcal{D}}{=} h^{-1}(Z), \quad Z \sim \mathsf{N}(0, 1).$$

Conditional Transformation Models

Implies the the density

$$f(y_i|\boldsymbol{x}_i) = f_{\text{ref}}(h_{\boldsymbol{x}_i}(y_i)) \left| \frac{\partial h_{\boldsymbol{x}_i}(y_i)}{\partial y_i} \right|$$

and cumulative distribution function

$$\mathbb{P}(y_i \leq c | \boldsymbol{x}_i) = F_{y_i}(c | \boldsymbol{x}_i) = F_{\mathrm{ref}}(h_{\boldsymbol{x}_i}(c)) = \mathbb{P}(z_i \leq h_{\boldsymbol{x}_i}(c)).$$

where $f_{\rm ref}$ and $F_{\rm ref}$ are the density and the CDF of the reference distribution (usually the standard normal).

Heteroscedastic Linear Model

• The transformation model

$$h(y|oldsymbol{x}) = oldsymbol{x}' \widetilde{oldsymbol{eta}} + yoldsymbol{x}' lpha, \quad ext{with } oldsymbol{x}' lpha > 0$$

implies

$$\mathsf{Y} \sim \mathsf{N}\left(-rac{oldsymbol{x}' ilde{eta}}{oldsymbol{x}' lpha}, rac{oldsymbol{1}}{(oldsymbol{x}' lpha)^2}
ight).$$

Likelihood-Based Inference

• Conditional transformation models can be estimated in a likelihood-based framework where the likelihood arises from

$$f_{Y|\mathbf{x}}(y) = f_{ref}(h(y|\mathbf{x})) \left| \frac{\partial}{\partial y} h(y|\mathbf{x}) \right|.$$

(the density implied by the transformation model).

- Main difficulty: Ensuring monotonicity of the transformation function.
- Can, for example, be implemented via Bernstein polynomial approximations for all functions envolved in the model specification.